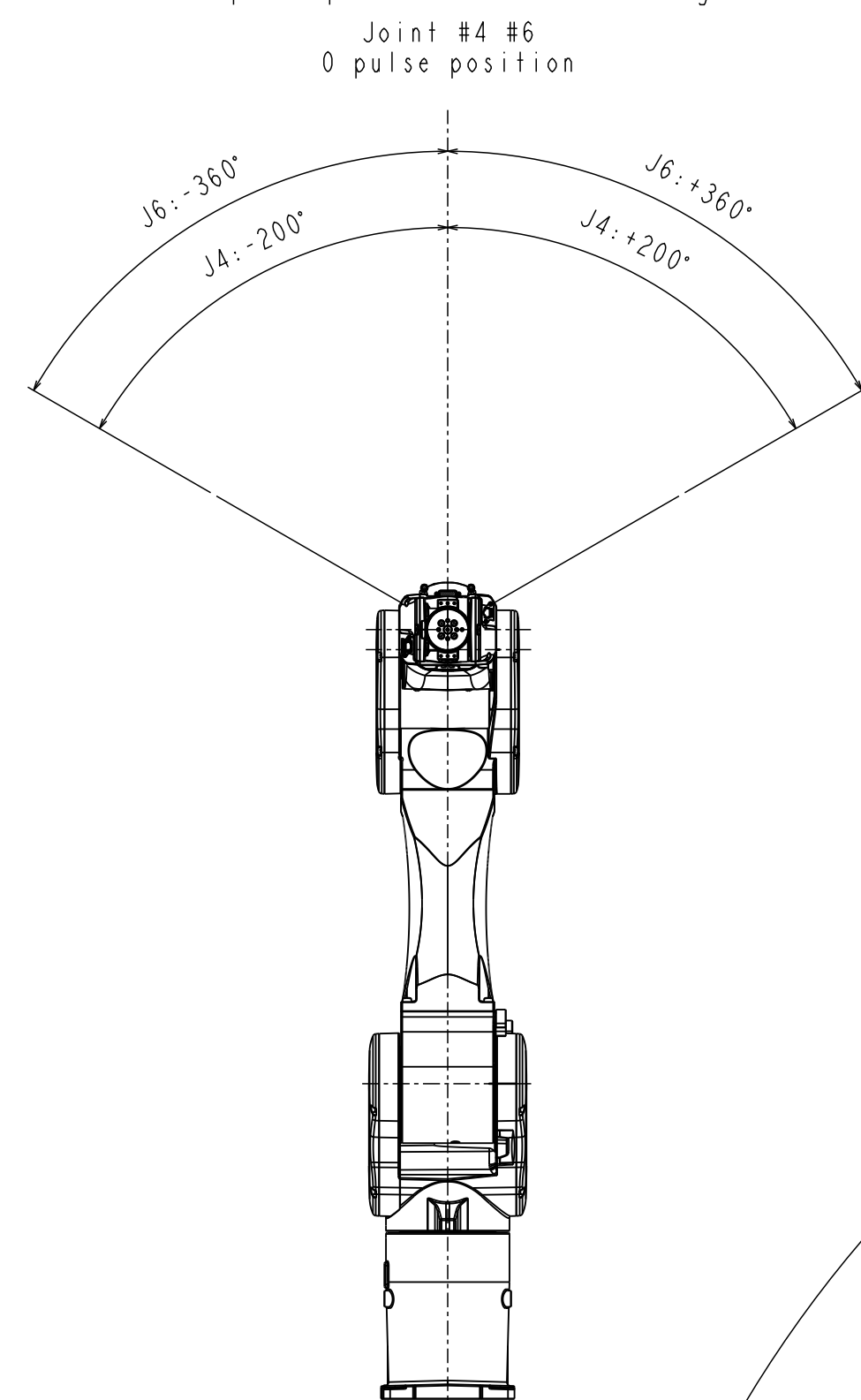
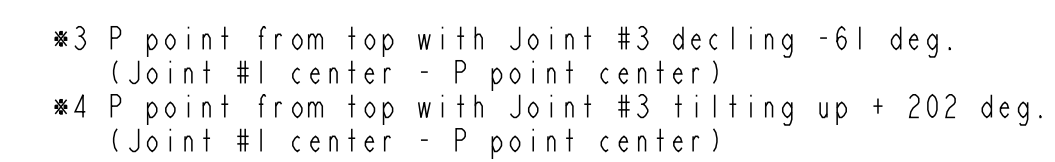
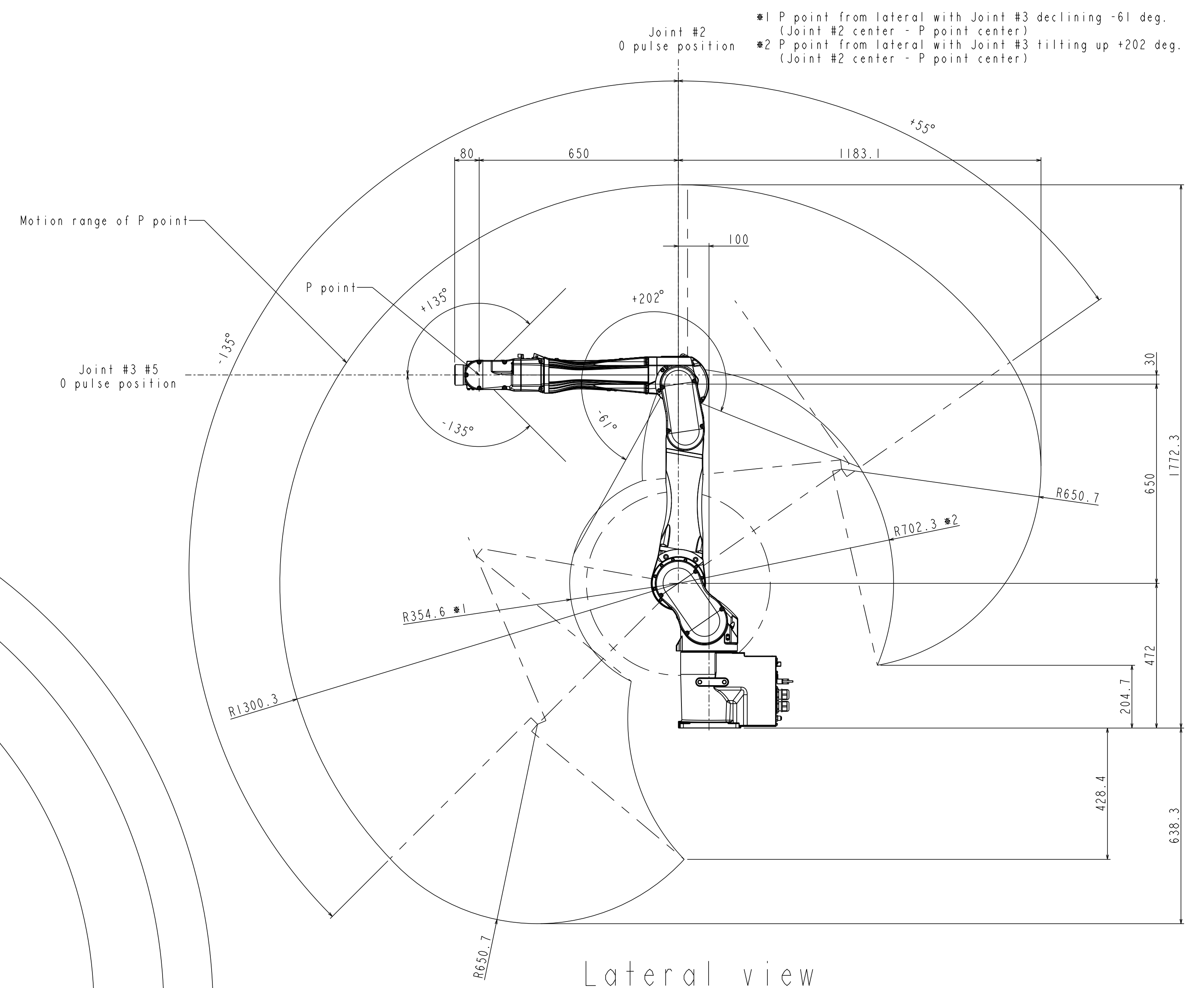
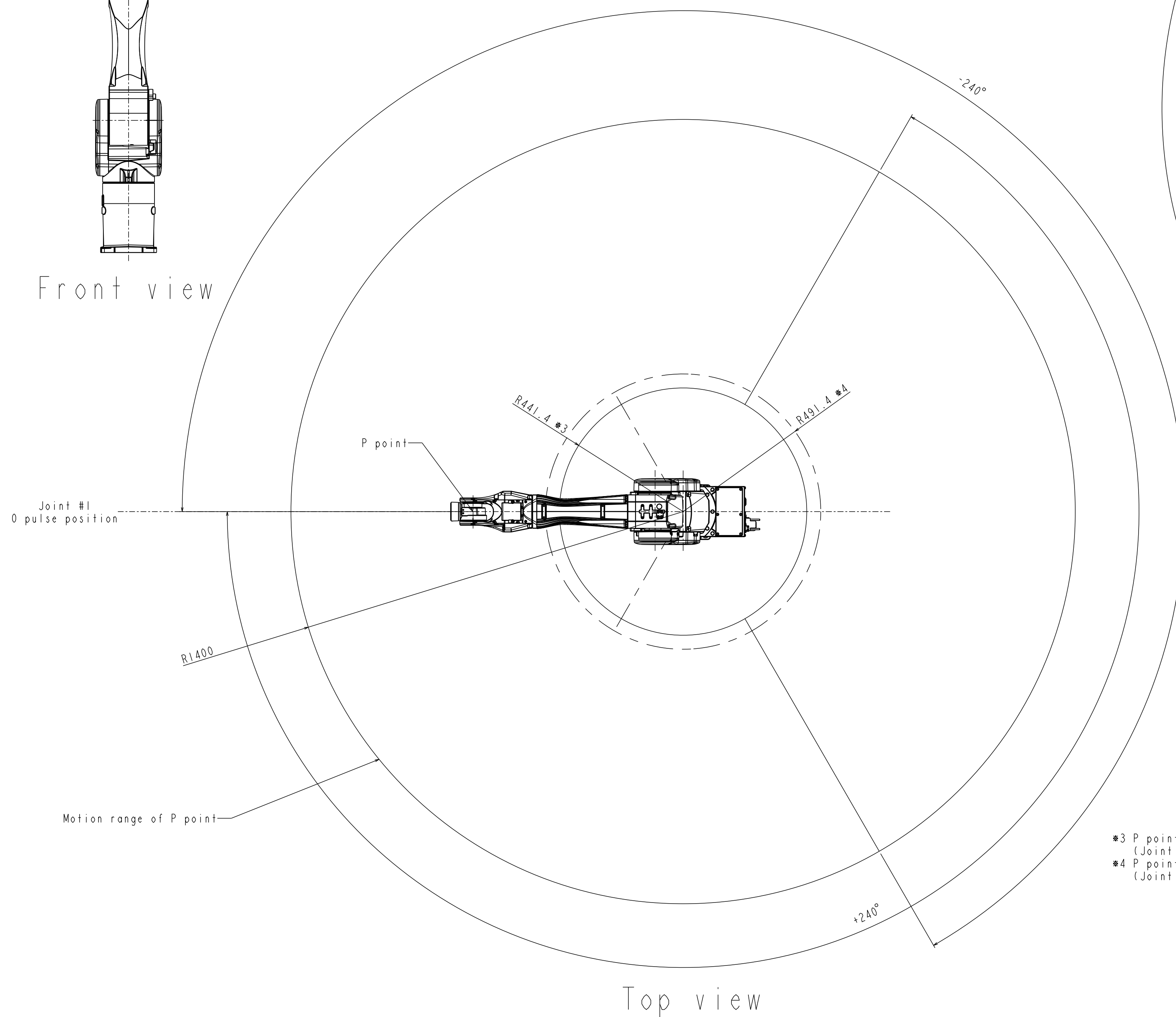


	Angle	pulse
Arm #1 revolves	$\pm 240^\circ$	± 15736800 pulse
Arm #2 Lower arm swings	$-135^\circ, +55^\circ (196^\circ)$	-10616940 pulse, $+4325420$ pulse
Arm #3 Upper arm swings	$-61^\circ, +202^\circ (263^\circ)$	-3997696 pulse, $+13238272$ pulse
Arm #4 Wrist revolves	$\pm 200^\circ$	± 5461400 pulse
Arm #5 Wrist swings	$\pm 135^\circ$	± 3932280 pulse
Arm #6 Wrist rotates	$\pm 360^\circ$	± 6553800 pulse

*All Joints are in 0 pulse position in this drawing. NOTE: ° = degree



Front view

[illegible]